

Approximation Algorithms for 3-D Common Substructure Identification in Drug and Protein Molecules

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Motivation

Problem:

- Given two drug or protein molecules, find the *maximal* common rigid sub-unit contained in both the molecules

Applications:

- *Pharmacophore* identification required for the design of new drugs
- Understanding mechanisms by which proteins work by identifying the common underlying structure in a group of proteins

The Equivalent Geometric Problem

Find the LCP of two 3-D point sets under ε -congruence

- A point set P is ε -congruent to a set Q if there exists an isometry I and a bijective mapping $I : P \rightarrow Q$ such that for each point $p \in P$, $d(I(p), p) \leq \varepsilon$ (also known as *bottleneck matching measure*)
- The *Largest Common Point Set (LCP)* of two point sets A and B under ε -congruence is the maximum cardinality subset of A which is ε -congruent to some subset of B

Approximating the LCP

- Approximate the constraint imposed by ε
- Approximate the size of the LCP

Approximating the ε constraint

Let the required isometry I for the exact solution map:

- point a to the ε -ball around a'
- point b to the ε -ball around b'
- point c to the ε -ball around c'

For the approximation algorithm consider the following

isometry I_{approx} :

- map a to a'
- align the vector ab with $a'b'$
- align c and c' by rotating c around the ab axis

The Approximation Algorithm

1. For all triplets of points from the set A
2. For all triplets of points from the set B
3. Compute the induced isometry I_{approx}
4. Apply this isometry to the set A and compute the number of distinct matching points in the set B which are within 8ε distance from points of A
5. Output the isometry which corresponds to the maximum number of matchings

8ε Approximation Algorithm

Theorem (follows from Goodrich, Mitchell and Orletsky)

- The algorithm returns a subset of cardinality at least as large as the LCP between A and B (under ε -congruence).
- Each point of this subset is at most within 8ε distance of a distinct point of the set B

Proof

If a, b and c are the farthest points of the $LCP \subseteq A$ then

- Each point should be originally ε distance away from a point of B
- Mapping a to a' moves a by at most ε from its required position
- Aligning the vectors ab with $a'b'$ moves b by at most 2ε
- Aligning c with c' moves c by at most 4ε
- Hence the total displacement of any point is at most $\varepsilon + \varepsilon + 2\varepsilon + 4\varepsilon = 8\varepsilon$

Approximating the Size of the LCP

Definition: For point sets A and B , isometry I , and a real number ε , let $G(I, \varepsilon, A, B)$ be the bipartite graph where the nodes correspond to the points of A and B , and the edges join all points a, b such that the distance between $I(a)$ and b is at most ε .

Definition: If the cardinality of a common subset is n then $\varepsilon_{\min}(n)$ denotes the minimum ε for which it exists.

A Partial Decision Algorithm

A Decision Algorithm:

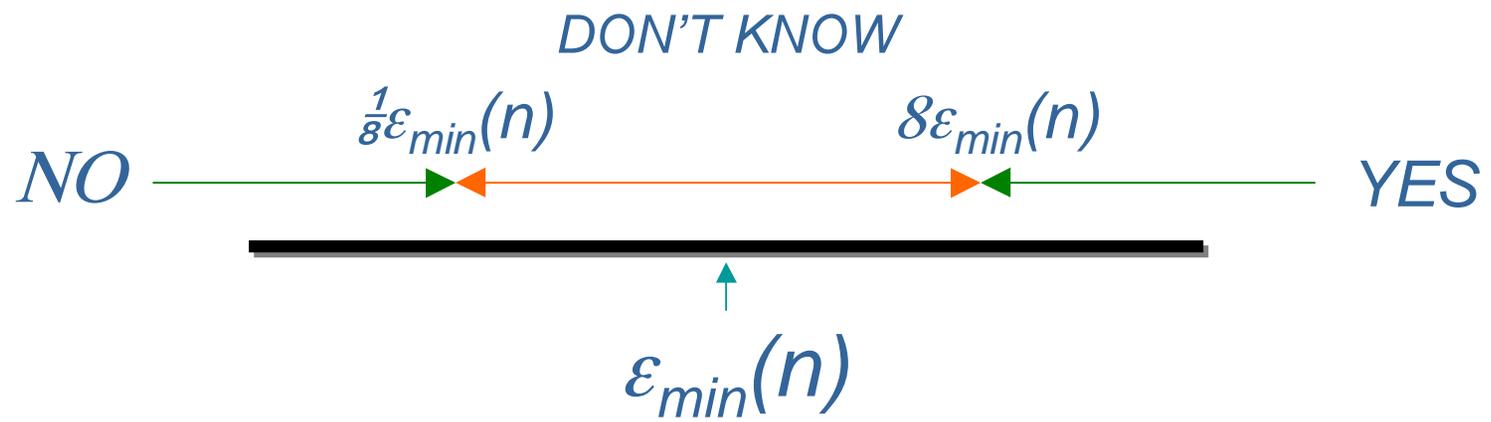
Input: Point sets A , B , real ε , and an integer n

Output: *YES* if there exists a common subset between A and B of size at least n under ε congruence, otherwise *NO*

Partial Decision Algorithm (based on Schirra):

Output: Might return *DON'T KNOW* if ε lies in the range

$$\left[\left(\frac{1}{8} \varepsilon_{\min}(n) \right), 8 \varepsilon_{\min}(n) \right)$$



Algorithm

1. For all triplets of points from A
2. For all triplets of points from B
3. Compute the induced transformation I_{approx}
4. If $G(I_{approx}, \varepsilon, A, B)$ has a matching of size $\geq n$ then return *YES*
5. *Decision = NO*
6. For all triplets of points from A
7. For all triplets of points from B
8. Compute the induced transformation I_{approx}
9. If $G(I_{approx}, 8\varepsilon, A, B)$ has a matching of size $\geq n$ then *Decision = YES*
10. If *Decision = NO* then return *NO* else return *DON'T KNOW*

Approximating the Size

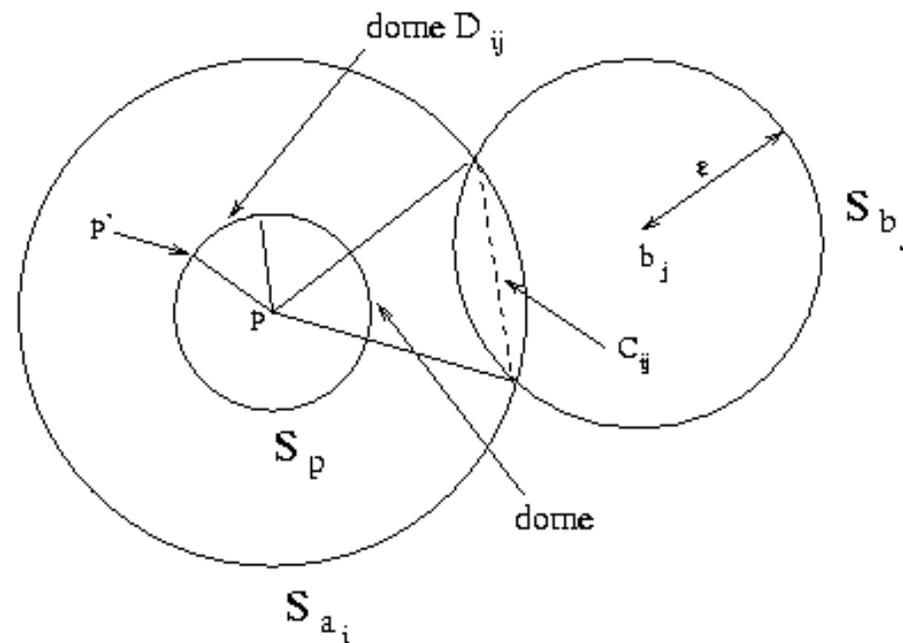
- Given ε find the maximum value of n for which the algorithm returns *YES* - This is the lower bound on the size of the LCP
- Find the minimum value of n for which the algorithm returns *NO* - This is the upper bound on the size of the LCP

Theorem

$$\max \{n : \varepsilon > \delta \varepsilon_{\min}(n)\} \leq n_l \leq n_{\max}(\varepsilon) < n_u \leq \min \{n : \varepsilon \leq \frac{1}{\delta} \varepsilon_{\min}(n)\}$$

An Exact Algorithm for Pure Rotation

Rotating the set A about a fixed point p :



Improving the Approximation Ratios

Lemma (follows from Schirra) Let isometry I , which is a composition of translation and rotation, result in a common subset of size n under ε -congruence. Let a be a point of this set. Then there is a rotation of the set A when translated so that a lies on $I(a)$, such that this enables in finding the same subset.

The factor of 8 in the approximation algorithms can be reduced to 2 by making use of the exact algorithm for rotation.

2ε Approximation Algorithm

Input: Point sets A, B , real number $\varepsilon > 0$

$n := 0$

for each point $a \in A$

for each point $b \in B$

$m := \text{LCP-ROT}(t_{ab}(A), B, b, 2\varepsilon)$

if ($m > n$) **then** $m := n$

return n

Theorem The algorithm returns a subset of cardinality at least as large as the LCP between A and B (under ε -congruence) and each point of this subset is at most within 8ε distance of a distinct point of the set B

Running Time

```
 $n := 0$   
for each point  $a \in A$   $O(n)$   
  for each point  $b \in B$   $O(n)$   
     $m := \text{LCP-ROT}(t_{ab}(A), B, b, 2\varepsilon)$   $O(n^{6.5})$   
    if ( $m > n$ ) then  $m := n$   
return  $n$ 
```

- The overall running time is $O(n^{8.5})$
- Hopcroft and Karp's algorithm for finding the maximum matching in a bipartite graph takes $O(n^{2.5})$ time

Improvements in Running Time

- Approximate graph matching when the nodes of the bipartite graph are points in some d -dimensional space and the edges are pairs of points within some specified distance (due to Efrat and Itai)
- Random Sampling

Approximation Algorithm for Maximum Matching

- Finds the maximum matching in a graph G where $G(I_{approx}, \varepsilon, A, B) \subseteq G \subseteq G(I_{approx}, (1+\delta)\varepsilon, A, B)$
- δ is a parameter of the algorithm for approximately answering nearest neighbor queries for point sets in \mathfrak{R}^d
- $O(n^{1.5} \log n)$ running time in contrast to $O(n^{2.5})$

Resulting Decision Algorithm

- $\varepsilon \geq 8\varepsilon_{min}(n)$ always returns *YES*
- $\varepsilon < \varepsilon_{min}(n) / 8(1+\delta)$ always returns *NO*
- $\varepsilon \in [\varepsilon_{min}(n) / 8(1+\delta), \varepsilon_{min}(n) / (1+\delta)] \cup [\varepsilon_{min}(n), 8\varepsilon_{min}(n)]$ either returns the correct answer or *DON'T KNOW*
- $\varepsilon \in [\varepsilon_{min}(n) / (1+\delta), \varepsilon_{min}(n)]$ might return *YES*, *NO*, or *DON'T KNOW*
- The transformation along with the bijective mapping that results in the algorithm to return *YES* results in each point of the set *A* to be within $(1+\delta)\varepsilon$ distance of the corresponding point of the set *B*

Resulting Approximation Algorithm

- $\max \{n : \varepsilon > 2\varepsilon_{\min}(n)\} \leq n_l \leq n_{\max}((1+\delta)\varepsilon)$
 $n_{\max}(\varepsilon) < n_u \leq \min \{n : \varepsilon < \varepsilon_{\min}(n) / 2(1+\delta)\}$
- Algorithm for finding the LCP under pure rotation runs in $O(n^{5.5} \log n)$ time in contrast to $O(n^{6.5})$
- Overall running time is $O(n^{7.5} \log n)$

Using Random Sampling

- X is a multiset of cardinality k randomly sampled from the set A
- Running time $O(n^{7.5})$

Theorem

- For any $k \geq \lceil (1/\alpha) \ln(1-q) \rceil$ the decision algorithm returns *YES* with probability at least q for all $\varepsilon \geq 2\varepsilon_{min}(n)$
- For all $\varepsilon < \frac{1}{2}\varepsilon_{min}(n)$ the algorithm always returns *NO*
- For $\frac{1}{2}\varepsilon_{min}(n) \leq \varepsilon < \varepsilon_{min}(n)$ it either returns *NO* or *DON'T KNOW*

A and B are of cardinality n and $\alpha \leq 1$ is the ratio of the size of the LCP and n

The final algorithm has a running time of $O(n^{6.5} \log n)$ but in contrast to definitely returning *YES*, it returns *YES* only with probability $\geq q$