Tutorial at EWSN 2007

Reliable Multihop Networking with Bluetooth

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Today’s Objective

Learn how to build a typical wireless sensor network application

• Get our hands dirty with “real” sensor network implementations

• Learn about their challenges and caveats

• This tutorial does not require prior experience in embedded programming and thus is suitable for researchers from all areas, e.g. people that have not yet had (extensive) platform experience

• Have fun…
• **In-depth BTnode Tutorial**
  - Originating in lectures at ETH Zurich
  - Set up in separate sessions
  - Minimum prerequisites required
  - Available online

• **This tutorial uses excerpts from**
  - First Steps
  - Bluetooth Multihop
  - Sensors
  - Debugging

• [http://www.btnode.ethz.ch](http://www.btnode.ethz.ch)
Material

• What you should have received
  – BTnode tutorial manual
  – Slide copies
  – CDROM containing software tools and doc’s
  – BTnode developer kit
    • BTnode rev3
    • USBprog board
    • 2xAA rechargeable cells
    • ATAVRISP programmer
    • USB cable
    • Serial Cable
  – A Teco Particles SSMALL sensor board

• Optional
  – USB-UART transceiver + 2nd USB cable
Your Requirements as Participants

- The hands-on experience requires you to
  - Install the necessary tools on your laptop
    - root/admin access
    - Handle a build system (make)
    - (program in C)

- We suggest you
  - Work in groups of two
  - Use a Windows laptop
    - Non-windows see http://www.btnode.ethz.ch/Documentation/Installation

- Hands-on exercises are marked in red on the slides
  - 1\textsuperscript{st} demonstration of the exercise – 2\textsuperscript{nd} time for participants
Outline

• Introduction
  – Basic concepts of embedded wireless sensor network platforms
  – Overview of the BTnode platform
    • Hardware architecture
    • BTnut system software

• Hands-on
  – Installing/getting to know the development tools
  – First steps in BTnode Programming
    • Plugging things together
    • Basic communication, ISP programming
    • The \texttt{bt-cmd} application – simple Bluetooth networking
  – My first BTnut multi-hop application
    • Bluetooth networking basics
    • Multihop networking
    • Sensor interfaces, packets and payload
    • Bluetooth Scatternet topology visualization

• Demonstration
  – Debugging and profiling of sensor network applications
Basic concepts of embedded wireless sensor network platforms

• “Mote class” devices
  – Microcontroller + low-power radio
  – Battery powered
  – Many custom applications
  – Large design space, many variants
  – Most prominent examples: Mica2, Mica2Dot, Tmote Sky

• Hardware is packaged with
  – System software and apps (e.g. TinyOS, BTnut, ...)
  – Basestations, network access
  – Server-side solutions (backends)
  – Tools (e.g. simulators, ...)
The BTnode Platform

Communication

Bluetooth Module

ATmega128L Microcontroller

Computations

IO/Peripherals

Prototype

2nd Generation

3rd Generation
The BTnode rev3 – Architecture Details

- **System core**
  - Atmel ATmega128
  - 256 kB SRAM
  - Generic IO/peripherals
  - Switchable power supplies
  - Extension connectors

- **Dual radio system**

  - **Bluetooth radio**
    - 2.4 GHz Zeevo ZV4002
  
  - **Low-power radio**
    - 433-915 MHz ISM Chipcon CC1000
  
  - On-board antennas
The BTnode rev3 – Atmel AVR Microcontroller Architecture

- **ATmega128l**
  - 8-bit AVR RISC @ 7.3 MHz
  - 64k address space
  - Integrated peripherals
  - Configurable using fuse bits

- Programs resident in flash memory
  - Max. size 128 Kbyte
  - One program at a time only

- System core – bus systems
  - UART0: Bluetooth
  - UART1: Ext. terminal, programming
  - SPI: Low-power radio, sensors
The BTnode rev3 – In-situ Power Profiling Function

![Graph showing power profiling](image)

Negri2005/2006
The BTnut System Software

- Versatile and flexible fast-prototyping
  - Lightweight operating system support in plain C
  - Standard GNU tools, avr-libc
  - Simple demo applications and tutorial

- Built on top of multi-threaded Nut/OS framework
  - Oriented towards networking applications
  - Non-preemptive, cooperative multi-threading
  - Events, timers
  - Priorities for threads
  - Dynamic heap allocation
  - POSIX style device drivers
  - OS tracer (µsec resolution)
BTnut – What’s the Difference to TinyOS?

- TinyOS is the de-facto standard for WSN software

- BTnut is plain vanilla C using the GNU toolchain, avr-libc
  - Less dependencies, no need for extra tools
  - No need to learn new languages/abstractions (nesC)

- BTnut offers support for concurrency through threads
  - Intuitive to program
  - No need to express all system functions using state-machines

- BTnut offers a clear and simple structure
  - Suitable for a quick jump-start and fast learning curve
  - Many features and tools target fast-prototyping
BTnodes are not targeted at ultra low-power...  
... but target versatile and flexible fast-prototyping.

- **Multi-threaded OS frame in C**
  - Standard open-source tools
  - Lightweight software distribution
  (12.3 MB binary, 32.5 MB source)

- **Rapid prototyping**
  - HW emulation on Linux PC

- **Demo applications and tutorial**
  - Different labs for graduate lectures
  - (Multi-)day tutorials
The BTnode Platform – Beyond Hard- and Software...

- Hardware and system software don’t yet make a platform...

- Documentation resources
  - Hardware: Datasheets, schematics, parts, design specifications
  - Software: API, libraries, compilers, demo apps
  - Many documented projects and applications

- The BTnode community
  - Development hosted on sourceforge.net (version control, tracker)
  - Wiki based web pages
  - Mailing list
  - Continuous integration using CruiseControl
BTnode Platform Success

- **Industrial technology transfer**
  - Commercialization with ETH spin-off “Art of Technology”
  - Commercial replicas resulting from open source policy

- **BTnodes in education**
  - Different labs and demos
  - Graduate lab in embedded systems (120 participants)
  - 50+ successful completed student projects

- **BTnodes in research domains**
  - 35+ wearable and ubiquitous computing applications and demos
  - Wireless (sensor) network research
  - 50+ scientific publications based on or related to BTnodes
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  – My first BTnut multi-hop application
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    • Multihop networking
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    • Bluetooth Scatternet topology visualization

• Demonstration
  – Debugging and profiling of sensor network applications
Hands-on: Installation of the Development Tools

- Development tools
  - AVR toolchain with avr-gcc, make, avrdude, ...
  - Terminal application (Hyperterm, Minicom, ZOC, ...)

- AVR toolchain installation
  - Open the directory `ewisn2007` on the BTnode CDROM
  - Install `WinAVR-20060125-install.exe` into `C:\WinAVR`

- Terminal application installation
  - Install `zoc507_win_english.exe`

- Testing the installation
  - Open a cmd shell and execute `avr-gcc --version`
**Hands-on: Installation of the BTnut Software**

- **BTnut software**
  - Precompiled libraries
  - Demo examples
  - Documentation

**Installation**

- Unpack `btnut_snap_btnode3_binary_1.8.tar.gz` into `C:\btnut_snap`

- **Directory structure**

![Diagram of directory structure]

- Demo applications
- Precompiled libraries/API
- Documentation
Hands-on: Browsing the BTnut API Documentation

- BTnut API documentation
  - Available in doc/html/index.html
  - Inline docs generated from source code using doxygen
  - Also available online http://www.btnode.ethz.ch/static_docs/doxygen/btnut

⚠️ Optional: Browsing the BTnut API – LED driver docs (Ex 2.4)
  - Find btnode/include/led/btn-led.h
  - Read and understand the documentation for btn_led_init() and btn_led_add_pattern()
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Plugging Things Together – The BTnode Development Setup

Developer Workstation

In-System Programmer attached to COMy

USB Terminal “Console” attached to COMx

BTnode
Hands-on: Plugging Things Together – The BTnode Terminal

- **USBprog adapter board**
  - CP2101 USB-UART transceiver
  - Power via USB
  - Breakout connectors for prototyping
  - Sensor interface connector

- **BTnode terminal connection**
  - USB cable
  - USBprog adapter board
  - BTnode

  - Watch out for the correct orientation!

- **Optional: Installation of the CP2101 driver**
Hands-on: BTnode Terminal – Basic Device Communication

★ BTnode terminal configuration
- Find the right COMx port
  - Start list_cp2101uart.vbs
- Start a terminal application (e.g. minicom or ZOC) using 57600, 8N1, no handshake
- Shortcut: Start BTnode_COM4.zoc to connect to COM4 (edit for other COMx ports)

★ BTnode terminal operation
- Press the reset button on the BTnode and observe the terminal
Hands-on: Plugging Things Together – The ISP Programmer

- AVR programming
  - Programs are resident in flash memory (ATmega128l = 128 Kbyte)
  - Different AVR programming variants
    - Serial using a hardware programmer
    - JTAG
    - Bootloader
    - (Parallel)

ATAVRISP programmer connection
- Connect to J2 on USBprog and a serial port on the PC
- No serial port available? Use the USB-UART transceiver

Testing the ISP programming tool installation (Ex 2.10)
- Open a cmd shell and execute `avrdude -h`
Hands-on: BTnode Programming – ISP Programming

Testing the ISP communication (Ex 2.12)
- Find the right COMy port
  - Start list_cp2101uart.vbs
  - Open cmd shell and execute
    avrdude -pm128 -cavrispv2 -P//./COMy

Programming a pre-compiled application (Ex 2.13)
- Open a cmd shell in ewsn2007 on the BTnode CDROM
- Erase the flash memory:
  - Execute
    avrdude -pm128 -cavrispv2 -P//./COMy -e
  - Program bt-cmd into flash
    - Execute
      avrdude -pm128 -cavrispv2 -P//./COMy -D -V -s -U
      flash:w:bt-cmd.btnode3.hex:i

The //./COMy syntax allows to map COM ports > 9 on Windows
Hands-on: Building and Uploading BTnut Applications

• The BTnut build process
  – Automated with GNU make
    • Toplevel Makefile in btnut_snap/app
    • Global Makerules and Makedefs in btnut_snap
    • Can be overridden using environment variables

🌟 Building the **bt-cmd** application (Ex 2.16)
  – Open cmd shell in btnut_snap/app/bt-cmd
  – Execute
    ```
    make btnode3
    ```
  – Define the serial port for programming (default is `/dev/ttyS0`)
    ```
    set BURNPORT=/./COMy
    ```
  – Execute
    ```
    make btnode3 upload
    ```
Hands-on: bt-cmd – Simple Bluetooth Networking

- Simple terminal commands
  - bt – Bluetooth radio commands
  - led – toggle LED patterns
  - bat – get the battery status
  - nut – show OS system information
  - log – BTnut logging features
  - More information on commands by pressing 2x tab

Try out these terminal commands with **bt-cmd**
- led on 3
- nut threads
- bt inquiry sync
- bt rname XX:XX:XX:XX:XX:XX
- Try to connect to other Bluetooth devices
Hands-on: bt-cmd – A Look Under the Hood

Open app/bt-cmd/bt-cmd.c in an editor

```c
/* \example bt-cmd/bt-cmd.c */

#include <hardware/btn-hardware.h>

int main(void){

  btn_hardware_init();

  // hello world!
  printf("\n#-------------------------------------------\n");
  printf("\n# Welcome to BTnut (c) 2006 ETH Zurich\n");
  printf("\n# booting Bluetooth module...\n");

  // bluetooth module on (takes a while)
  btn_hardware_bt_on();

  // terminal init
  sprintf(prompt, "[bt-cmd@"SADDR_FMT"]$ ", SADDR(addr));
  btn_terminal_init(stdout, prompt);
  bt_cmds_init(stack);
  bt_cmds_register_cmds();
  btn_cmds_register_cmds();

  // terminal mode
  btn_terminal_run(BTN_TERMINAL_NOFORK, 0);

  return 0;
}
```
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• Demonstration
  – Debugging and profiling of sensor network applications
Now that you have an overview of BTnodes, the BTnut software and required tools, we want to build an application.

- Typical wireless sensor network application
  - Sampling on different sensors in a regular interval
  - Multi-hop networking
  - Debugging output
  - Data collection and visualization

- Hands-on exercises using an application template
Bluetooth Networking – Introduction

• **Bluetooth in a nutshell**
  – Low-power, low-range personal communication
  – Frequency hopping spread spectrum
  – 2.4 GHz ISM band
  – 79 channels
  – 1 Mbit/sec data rate
  – 10-100 m range
  – Connection-oriented

• **Many high-level features built in**
  – Encryption, authentication
  – Error correction
  – Flow control

• **Available on many consumer devices**
• Communication organized in Piconets
  – Master-slave configurations
  – Up to 7 active slaves
  – 255 inactive (parked) slaves

• Piconets can be combined in Scatternets

• Four states

  IDLE
  MASTER
  SLAVE
  MASTERSLAVE

• Useful operations
  – inquiry() – find other nodes
  – connect() – open connection
  – roleSwitch() – change MS relation
  – sendData() – data transport

• Detailed capabilities/features vary across Bluetooth devices
Bluetooth Networking – Simple Scatternet Tree Construction

- A simple and effective approach
- Link layer connectivity
  - Random search and connect

```
loop {
  while (my_slaves < max_degree) do
    found_nodes = inquiry();
    forall nodes in found_nodes do
      connect();
  }
}
```

- Distributed coordination
  - Inquiry() and connect() operations can exhibit long delays
  - No a priori guarantee for success
  - Serialization of parallel processes

Bluetooth Networking – Host Controller Interface

- Standardized asynchronous, buffered packet interface
  - providing access to lower levels of the protocol stack

![Diagram showing the Host Controller Interface and its components](image)

- Bluetooth module
- Host processor
- Physical interface
- UART
- Bluetooth module
My First BTnut Application – The Bluetooth Protocol Stack

Bluetooth Radio

Baseband

Bluetooth Radio

Link Manager Protocol

Audio

L2CAP

RFCOMM

TCS

SDP

AT Commands

PPP

TCP/IP

OBEX

Application

HCI
My First BTnut Application – The BTnut Protocol Stack

- Bluetooth Radio
- Baseband
- Link Manager Protocol
- L2CAP
- RFCOMM
- Connection Manager
- Multi-Hop
- RPC
- Code-Distribution
- L2CAP connectionless
- Protocol Service Multiplexer
- Audio
- Services with a PSM_ID

HCI

Bluetooth Protocol Stack Diagram
My First BTnut Application – The Host Controller Interface Layer

Connection Manager
Multi-Hop
RPC
L2CAP connectionless
HCI - btstack

HCI

Manages connections to other Bluetooth devices
My First BTnut Application – Application Template Overview

```c
int main(void) {
}
```

**Diagram:**
- Connection Manager
- Multi-Hop
- RPC
- L2CAP connectionless
- HCI - btstack

**Code Snippet:**
```c
int main(void) {
}
```
Hands-on: Application Template Overview

int main(void) {
}

⭐️ A template `sensor-node.c` has been prepared for you
- Copy the folder `ewsn2007/ewsn-example` into the folder `app`
- It contains `sensor-node.c`, `defs.h`, `Makefile` and solutions
- Open `app/ewsn-example/sensor-node.c` in an editor
int main(void) {
    // hardware init
    btn_hardware_init();
    btn_led_init(1);

    // init terminal app uart
    u_long baud = 57600; // serial baud rate
    NutRegisterDevice(&APP_UART, 0, 0);
    freopen(APP_UART.dev_name, "r+", stdout);
    _ioctl(_fileno(stdout), UART_SETSPEED, &baud);
    btn_terminal_init(stdout, "[senso]$");  

    // hello message
    printf("\n# -----------------------------------------\n");
    printf("\n# Welcome to EWSN 2007 (c) ETH Zurich\n");
    printf("# program version: %s\n", PROGRAM_VERSION);
    printf("# -----------------------------------------\n");

    printf("\nbooting bluetooth module.\n");
    btn_hardware_bt_on();
    ...
}
```c
int main(void) {
    ...
    struct btstack* bt_stack;
    bt_stack = bt_hci_init(&BT_UART);

    bt_acl_init(bt_stack, BT_HCI_PACKET_TYPE_DM3);

    ...
}
```
int main(void) {
    ...
    struct btstack* bt_stack;
    bt_stack = bt_hci_init(&BT_UART);

    bt_acl_init(bt_stack, BT_HCI_PACKET_TYPE_DM3);

    bt_psm_t* psmux;
    psmux = bt_psm_init(bt_stack, MAX_NR_SERVICES, NR_BUFFERS);
    l2cap_cl_init(bt_stack, psmux);

    ...
}
int main(void) {
    ...
    struct btstack* bt_stack;
    bt_stack = bt_hci_init(&BT_UART);

    bt_acl_init(bt_stack, BT_HCI_PACKET_TYPE_DM3);

    bt_psm_t* psmux;
    psmux = bt_psm_init(bt_stack, MAX_NR_SERVICES,
                        NR_BUFFERS);
    l2cap_cl_init(bt_stack, psmux);

    con_mgr_init(bt_stack, psmux, CM_PSM,
                 bt_hci_register_con_table_cb, CM_COD);

    ...
}
int main(void){
    ...
    struct btstack* bt_stack;
    bt_stack = bt_hci_init(&BT_UART);

    bt_acl_init(bt_stack, BT_HCI_PACKET_TYPE_DM3);

    bt_psm_t* psmux;
    psmux = bt_psm_init(bt_stack, MAX_NR_SERVICES, NR_BUFFERS);
    l2cap_cl_init(bt_stack, psmux);

    con_mgr_init(bt_stack, psmux, CM_PSM,
                 bt_hci_register_con_table_cb, CM_COD);

    mhop_cl_init(bt_stack, psmux, MHOP_PSM, NR_BUFFERS,
                 con_mgr_register_con_table_cb);

    ...
}
```
int main(void) {
    ...
    struct btstack* bt_stack;
    bt_stack = bt_hci_init(&BT_UART);

    bt_acl_init(bt_stack, BT_HCI_PACKET_TYPE_DM3);

    bt_psm_t* psmux;
    psmux = bt_psm_init(bt_stack, MAX_NR_SERVICES,
                        NR_BUFFERS);
    l2cap_cl_init(bt_stack, psmux);

    con_mgr_init(bt_stack, psmux, CM_PSM,
                 bt_hci_register_con_table_cb, CM_COD);

    mhop_cl_init(bt_stack, psmux, MHOP_PSM, NR_BUFFERS,
                 con_mgr_register_con_table_cb);

    rpc_init(psmux, 8, RPC_PROC_PSM, RPC_RESULT_PSM);
    ...
}
```
Hands-on: Visual Control – Debugging with LEDs

First steps with `sensor-node.c`

- Understand the basic structure of the source code files
- Compile, upload and inspect the state on the LEDs

<table>
<thead>
<tr>
<th>State</th>
<th>LED Pattern</th>
<th>LEDs</th>
</tr>
</thead>
<tbody>
<tr>
<td>Initialization</td>
<td>Heartbeat</td>
<td></td>
</tr>
<tr>
<td>No connection</td>
<td>4Bit-ID+Heartbeat</td>
<td></td>
</tr>
<tr>
<td>Inquiry</td>
<td>Knight-Rider</td>
<td></td>
</tr>
<tr>
<td>Connected</td>
<td>4Bit-Tree-ID</td>
<td></td>
</tr>
<tr>
<td>Connectivity with base station</td>
<td>Green LED</td>
<td></td>
</tr>
</tbody>
</table>
Check the graph to see your BTnode pop up

# of Senornodes: 3
Hands-on: Sampling a Single Sensor

- Attach the sensor board to the USBprog

- Extend `sensor-node.c` with a sensor
  - Sample one sensor (microphone) every 5 seconds
  - Print the value on the terminal

```
#include <teco_ssmall/micsampler.h>
#include <dev/adc.h>

THREAD(sensorLoop, arg){       // sensor thread
    ADCInit();
    mic_init();
    for(;;){
        NutSleep(5000);
        printf("mic value = %u\n", mic_read());
    }
}
```

Before `btn_terminal_run()`:
```
btn_hardware_io_power(1); // sensor board power
NutThreadCreate("T_sensor", sensorLoop, 0, 256)
```
Hands-on: Sampling Multiple Sensors

1. Sample all 3 sensors:
   - Microphone
   - Light
   - Temperature

2. Store the sensor values in a predefined data-structure

3. Print the sampled data on the terminal

🌟 Copy the code on the right into the template

```c
#include <dev/twif.h>
#include <teco_ssmall/tls2550.h>
#include <teco_ssmall/tc74.h>

THREAD(sensorLoop, arg) {
    TwInit(20); // init twi with slave addr

    while(tsl_init()) NutSleep(10000); // start light sensor

    ADCInit();
    mic_init(); // init mic

    sensor_data_t sensor_data; // see defs.h
    sensor_data_t* data = &sensor_data;
    u_char channel0, channel1;
    signed int temp;

    for(;;){
        NutSleep(5000);
        data->mic = mic_read(); // sample mic
        tsl_read(&channel0, &channel1); // sample light
        data->light = tsl_calculate_lux(channel0, channel1);
        tc_read(&temp); // read temperature
        data->temp = temp;
        printf("mic = %u, light = %d, temp = %u\n",
               data->mic,
               data->light,
               data->temp);
    }
}
```
**Hands-on: Multi-hop Data Transport**

Send the data-structure with the sensor values in a multi-hop packet to a base-station

```c
// address of the base station (note: big endian)
bttaddr_t sink_addr = {0x8b, 0x01, 0x00, 0x3f, 0x04, 0x00};

// send packet
mhop_cl_send_pkt((u_char*)data,
    sizeof(sensor_data_t),
    sink_addr,
    SENSE_PSM,
    MHOP_CL_UNICAST, MHOP_CL_TTL_INFINITY);
```
My First BTnut Application – Sensor Data Visualization

# of Sensor nodes: 3
Data-callback prints sensor values on terminal:

```c
bt_acl_pkt_buf* sensor_data_cb(bt_acl_pkt_buf* pkt_buf,
                                u_char* data, u_short data_len,
                                u_short service_nr, void* cb_arg){
    u_char* source = mhop_cl_get_source_addr(pkt_buf->pkt);
    sensor_data_t* sensor_data = (sensor_data_t*) data;

    printf(":S "SADDR_FMT" %u %d %u\n", SADDR(source),
            sensor_data->mic,
            sensor_data->light,
            sensor_data->temp);

    return pkt_buf;
}
```

Data-callback is registered in main() with a PSM number:

```c
bt_psm_service_register(psmux, SENSO_PSM, sensor_data_cb, NULL);
```
Congratulations!
Beyond the Blinking LED – Embedded Debugging

- LEDs are nice but they
  - Offer a limited view inside only (e.g. Mica2Dot with one LED only)
  - Lack context/timing information (order of events?)
  - Consume lot’s of power

- Other debugging techniques
  - Instruction-code simulators (with debugging capabilities)
  - In-circuit emulators (ICE)
  - Breakpoints with JTAG
  - `PRINTF()` statements
  - Levels of verbosity, memory consumption, timing

- Operating system monitors
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Beyond the Blinking LED – The BTnut OS Tracer

- The tracer tool is an extension to the BTnut software
  - Storage of information about important OS events
    - Thread switches, interrupts
    - Type of event, system time, additional information
  - Retrieval of information for offline analysis at a later time
  - Runtime configurable
  - Must be enabled at compile time using `--DNUTTRACER`

```
[btnode]$trace oneshot TRACE mode ONESHOT, restarted
[btnode]$trace TRACE STATUS
Mode is ONESHOT
Size is 500
contains 77 elements
[btnode]$trace print 10
TRACE contains 500 items, printing 10 items.
TAG PC/Info Time[s:ms:us]
-----------------------------------------------
Thread Yield idle  13:524:336
Thread Sleep LED  13:524:604
Thread Yield idle  13:581:857
Thread Sleep LED  13:582:125
Thread Yield idle  13:639:392
Thread Sleep LED  13:639:659
Thread Yield idle  13:696:909
```
The Deployment-Support Network

- Deployment-Support Network
  - Temporary, minimal invasive
  - Virtual connections to nodes
  - Reliable, wireless, scalable

Further Reading


Welcome to the BTnode Platform

Overview
The BTnode is an autonomous wireless communication and computing platform microcontroller. It serves as a demonstration platform for research in mobile and distributed sensor networks. The BTnode has been jointly developed at the Engineering and Networks Laboratory (TEL) of the ETH Zurich and the Research Group for Distributed Embedded Systems at the University of California, Berkeley. It is currently being used in two major research projects: NCCR-MICS WP5 and WP7.

Features
- BTnode rev3
- BTnode USB prog v2
- BTnode rev3 Developer Kit
- BTnode rev3 Features at a Glance

Purchasing
The BTnode products are available for purchase through a contract manufacturer:
- Art of Technology AG, Zurich, Switzerland
- Sales Contact: Fax: +41-44-440 28 35
- Email: btnode@arta-technology.ch

Projects
- Java - Deployment Support (IDR)
- Sensor Network
- Museum
- NCCR-MICS WP5
- Development
- sourceforge.net
- CVS
- BTnode Build Status
- Wiki
- Search
- Wiki Sandbox
- Recent Changes

BTnode Online Resources

http://www.btnode.ethz.ch