Master/Semester Thesis:

**Triggered IMU Sensing on Dual-Processor Platform**

**Motivation** In a recent Master Thesis we have developed a triggered geophone sensor based on the Dual-Processor Platform architecture for wireless sensor nodes. These sensors are currently being deployed in collaboration with geoscience research partners and Swiss authorities for natural hazard process monitoring used in PermaSense [1].

In this thesis we want to extend and explore the sensing capabilities with an Inertial Motion Unit (IMU) that features a tri-axial inclinometer and accelerometer. This IMU is already integrated in the current hardware platform and can be used both in scheduled sampling (periodic/continuous) mode as well as in triggered mode. In triggered mode the sensor will only wake-up the processor and generate data when a pre-defined signal threshold is exceeded. This allows to operate in low-power modes saving resources when no significant signals are present saving power and also network bandwidth. From the analysis side the challenge is to develop methods for this co-detection of new kind of event-based data from many sensors.

**Requirements** You should have knowledge in

- Signal processing
- Programming (C/C++)
- Embedded Systems

Interested? Please have a look at [http://www.tec.ethz.ch/research.html](http://www.tec.ethz.ch/research.html) and contact us for more details!

**Contacts**

- Jan Beutel: beutel@tik.ee.ethz.ch, ETZ G84
- Matthias Meyer: matthias.meyer@tik.ee.ethz.ch, ETZ G81

**References**